

# Lecture 9: Transformations, Weighted ANOVA

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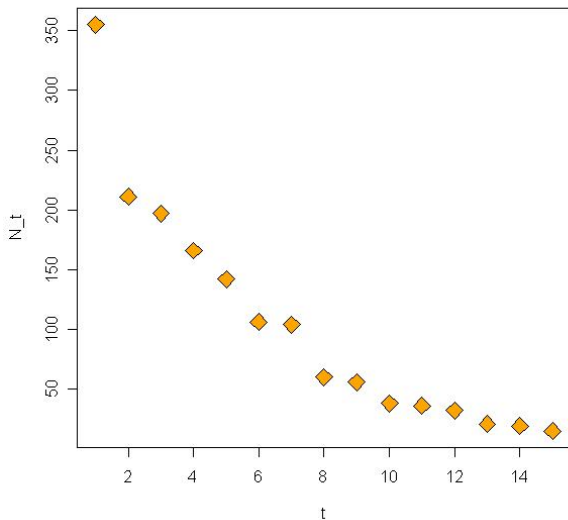
Linear regression (ANOVA) model:

$$Y = \beta_0 + \beta_1 X + \cdots + \beta_p X_p + \text{error},$$
$$\text{error} \sim N(0, \sigma^2).$$

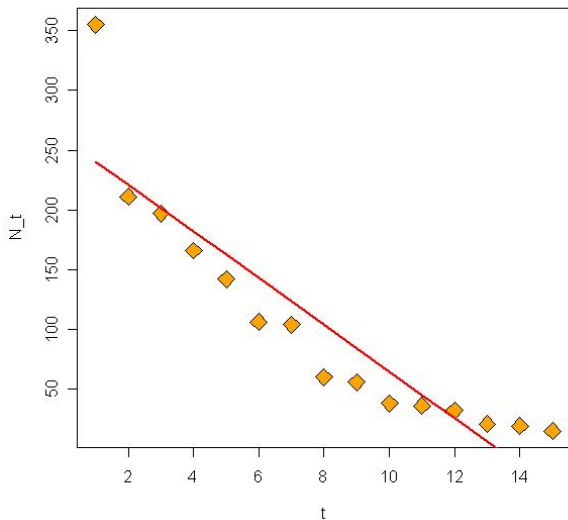
- 1 Mean depends on predictors in a *linear* way.
- 2 Error is Gaussian.
- 3 Variance is constant.
- 4 Variance is independent.

When these assumptions are violated, linear Gaussian models can *sometimes* still apply after transforming the variables.

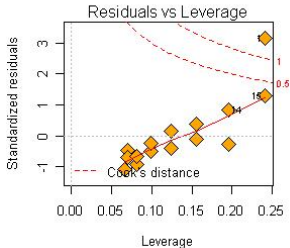
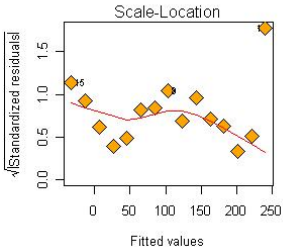
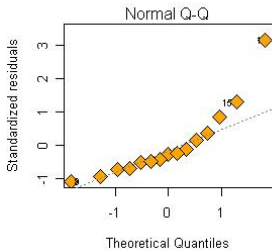
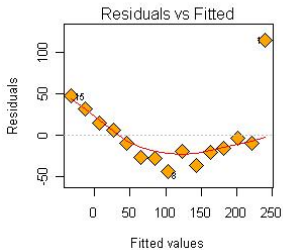
# Experiment: Number of surviving marine bacteria following exposure to X-rays.



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## Trend visible in residual plots.



# Exponential growth (decay) model

- Suppose the expected number of cells grows like

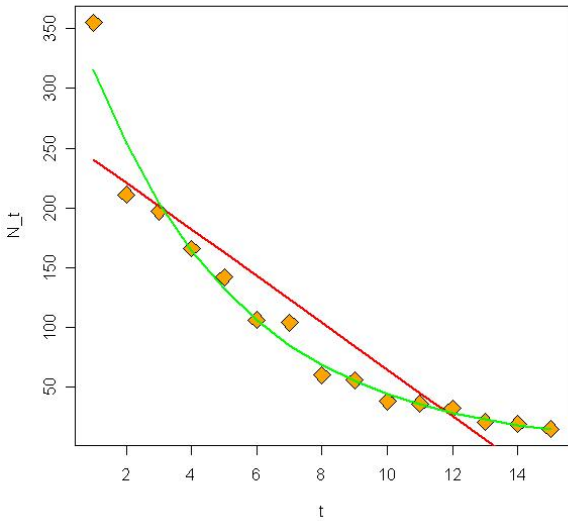
$$E(n_t) = n_0 e^{\beta_1 t}, \quad t = 1, 2, 3, \dots$$

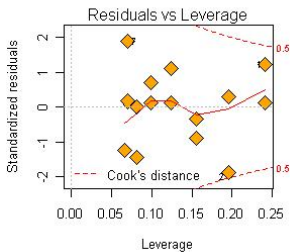
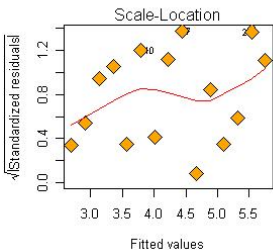
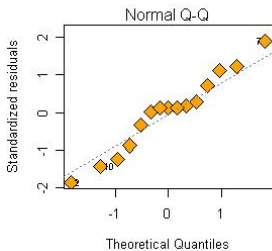
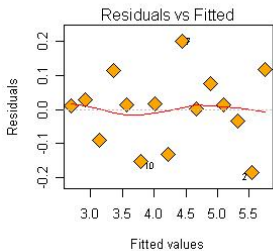
- If we take logs of both sides

$$\log E(n_t) = \log n_0 + \beta_1 t.$$

- (Reasonable ?) model:

$$\log n_t = \beta_0 + \beta_1 t + \varepsilon_t, \quad \varepsilon_t \sim N(0, \sigma^2) \text{ independent}$$



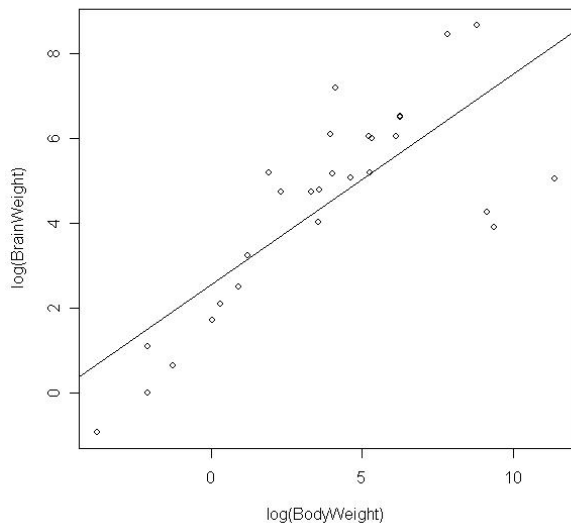


## Some models that can be linearized

- $y = \alpha x^\beta$ , use  $\tilde{y} = \log(y)$ ,  $\tilde{x} = \log(x)$ ;
- $y = \alpha e^{\beta x}$ , use  $\tilde{y} = \log(y)$ ;
- $y = x/(\alpha x - \beta)$ , use  $\tilde{y} = 1/y$ ,  $\tilde{x} = 1/x$ .
- More examples in chapter 6 of the textbook.



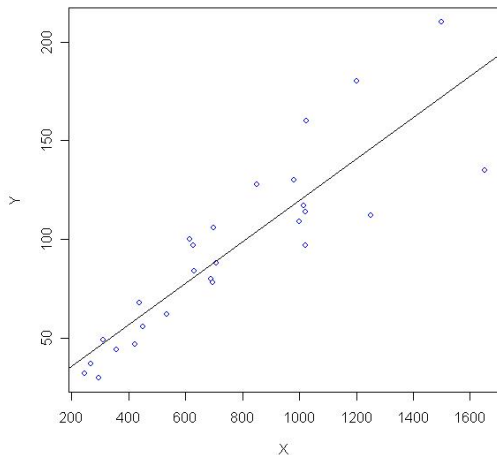
## Highly asymmetric data - log transformation



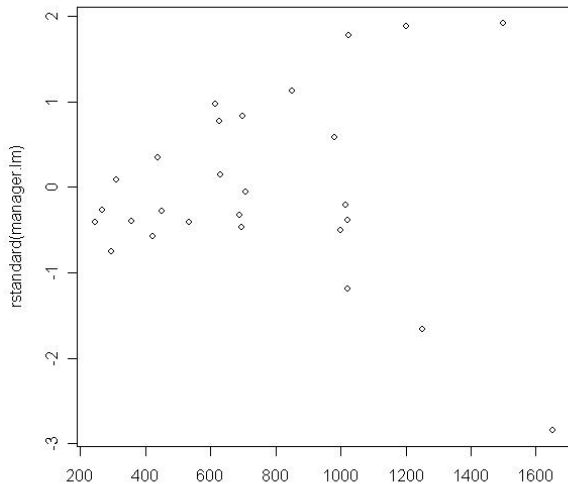
Look at R script...

## Nonconstant Variance

In a study of 27 companies, the number of workers ( $X$ ) and the number of supervisors ( $Y$ ) were recorded.



# Transformations for Stabilizing Variance - Manager Example



# Summary of Common Transformations

- $\text{Var}(\epsilon) \propto X^2$ , then

$$Y' = \frac{Y}{X}, \quad X' = \frac{1}{X}.$$

- $\text{Var}(\epsilon) \propto X$ , then

$$Y' = \sqrt{Y}, \quad X' = X.$$

- Either  $Y$  or  $X$  has large, asymmetric variation (e.g. Brain data),

$$Y' = \log(Y), \quad X' = \log(X).$$

There is often more than one solution. The best approach is to use empirical evidence and domain knowledge.

## Variance Stabilizing Transformations

Suppose  $E(y) = \mu$ , and  $Var(Y) = f(\mu)$ . Seek transformation  $g(Y)$  such that  $Var[g(Y)]$  does not rely on  $\mu$ :

$$g(Y) \approx g(\mu) + g'(\mu)(Y - \mu).$$

$$Var[g(Y)] = [g'(\mu)]^2 Var(Y),$$

thus, we can pick  $g(\cdot)$  such that

$$[g'(\mu)]^2 = \frac{1}{f(\mu)}.$$

or

$$g(y) = \int_0^y \frac{1}{\sqrt{f(\mu)}} d(\mu).$$

Example:  $Y \text{ Poisson}(\mu)$ ,  $Var(Y) = \mu = E(Y)$ , thus a good transformation would be  $\text{sqrt}(Y)$ .

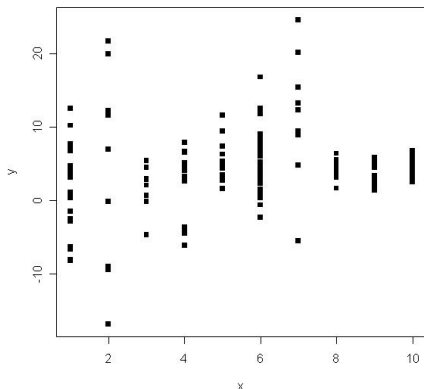
## Another example: College expenses

What determines total annual expense for college students?

- $Y$ : *Average* annual expense over students surveyed in the institution.
- Size of city where the school is located.
- Size of student body
- ...

Each data point is an average over sampling units taken over pre-defined groups. The error variance of the observations decrease over group size. Weigh observations by  $\sqrt{n_i}$ , the size of group  $i$ .

## Another example: Hypothetical lab experiment



Data at each  $x$  can be used to estimate  $\sigma_x$ , weigh observations by  $\sigma_x^{-1}$ .

# Solving Weighted Least Squares

Minimize:

$$L_w(\beta) = \sum_{i=1}^n w_i (Y_i - \beta_0 + \beta_1 X_{i,1} + \cdots + \beta_p X_{i,p})^2.$$

In matrix form:

$$L_w(\beta) = (Y - X\beta)' W (Y - X\beta),$$

where  $W$  is diagonal matrix with entries  $w_1, \dots, w_n$ . The solution to the above remains linear in  $Y$ :

$$\hat{\beta} = (X' W X)^{-1} X' W Y.$$

As expected, this is the same as rescaling row  $i$  of the data by  $\sqrt{w_i}$ .

Note that  $W$  does not have to be diagonal. Weighted least squares is a special case of *generalized least squares*.

# Generalized Least Squares

When  $W$  is any symmetric positive-definite square matrix, then solutions to

$$L_w(\beta) = (Y - X\beta)'W(Y - X\beta),$$

are called generalized least squares solutions. Let

$$W = LL', \quad L \text{ lower triangular}$$

be a Cholesky decomposition of  $W$ . Then the above is equivalent to least squares on the transformed data,

$$X' = L'X, \quad Y' = L'Y.$$

If we assume Gaussian errors, then this corresponds to maximum likelihood of a multivariate Gaussian density with covariance matrix  $W^{-1}$ .

## When the error variance structure is not known.

Assume that variance is a function of  $X$ :

$$\sigma_i = f(X_i).$$

Multiple predictors: rely on prior knowledge to choose  $X$ . Relationship should be graphically obvious.

Iterative re-weighted least squares:

- 1 Fit unweighted least squares,
- 2 Estimate  $\hat{\sigma}_i = f(X_i)$  from absolute residuals (assuming an appropriate functional form),
- 3 Let  $w_i = 1/\hat{\sigma}_i^2$ .
- 4 Repeat the above two steps until convergence.

